

MANUAL CHUCK WITH QUICK JAW CHANGE

MODEL - FFT



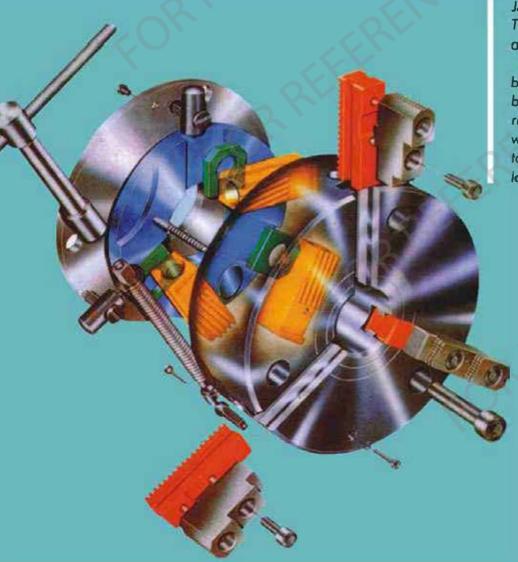
G MT has been producing hand operated chucks of worm and wormwheel with com design for well over three decades. GMT chucks have met and satisfied the requirements of thousands of customers all over India through sheer quality and reliability. In order to meet the growing needs of present day small and medium batch production, GMT now offers a Manual Chuck also with High concentricity and reliability with Quick Jaw change. This ensures that Repositioning Reversing (or) Changing of the jaws can be done quickly and accurately.

DESIGN FEATURES:

The master jaws are moved radially by operating screw which is fitted in a wedge black. Three wedge blacks are inter-connected by pivot blacks and a transmission ring, effecting the concentric movement of all jaws.

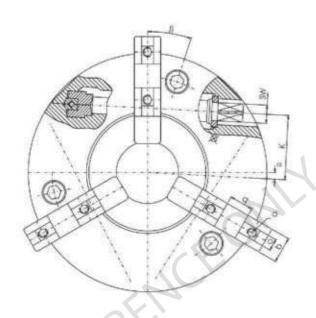
The wedge block is made of nickel chrome steel with case hardened and the rack profile an the wedge block is ground on a CNC creep feed grinding machine to ensure high concentricity and repeatability an jaws.

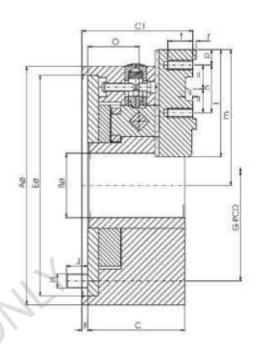
The jow has teeth at the bottom which is in mesh with the rack, is made of nickel chrome steel and is case hardened and ground. The teeth profile is ground on a creep feed CNC grinder. The wedge block can be brought out of mesh to enable the top jaws to be taken out by pressing the spring loaded plunger. The chuck body is made of medium carbon steel. The jow slides are precision ground.



JAW SAFETY DEVICE:

The top jaws can be moved freely and are locked by means of a spring loaded plunger. The top jaws cannot fly out because they are automatically locked by safety lock arrangement. In order to relocate the top jaws, the spring plunger which is located behind the tap jaws is to be pressed which releases the safety lock from 200 \$\phi\$

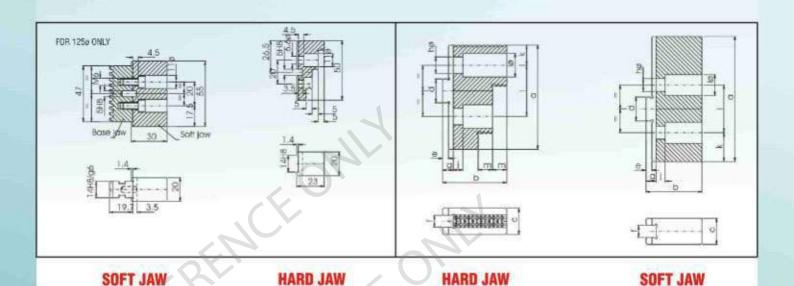




DIMENSIONAL SPECIFICATIONS

All Dimensions in mm.

| DIMENSIONAL SPECIFICATIONS | | | | | V 001.000.000000000000000000000000000000 | | | |
|---------------------------------------|------|--------|--------|------|--|--------|--------|-------|
| SIZE | /5 | 125 | 160 | 200 | 250 | 315 | 400 | 500 |
| Αφ | | 125 | 161 | 206 | 255 | 318 | 400 | 500 |
| Вф | | 32 | 42 | 52 | 60 | 85 | 100 | 150 |
| C | | 46.5 | 63 | 81 | 92 | 111 | 118 | 119 |
| a | | 53 | 73 | 93 | 105 | 125 | 135 | 136 |
| ЕфН5 | | 115 | 145 | 185 | 235 | 300 | 380 | 460 |
| F | | 4 | 5 | 5 | 6 | 6 | 6 | 6 |
| GPCD. | | 100 | 125 | 160 | 200 | 250 | 315 | 400 |
| н | | M8 | M10 | M12 | M16 | M20 | M24 | M24 |
| 1 | | 11 | 13 | 18 | 27 | 33 | 34 | 34 |
| K | | 33 | 43 | 54 | 67 | 86 | 111 | 153.5 |
| 0 | | 22.5 | 31.5 | 43 | 47. | 59 | 57.5 | 58.5 |
| Sw | | 8 | 10 | 12 | 14 | 17 | 19 | 19 |
| b | | 14 | 20 | 22 | 26 | 32 | 45 | 45 |
| d | | M6 | M8 | M8 | M12 | M12 | M16 | M16 |
| I | | 47 | 74 | 90 | 110 | 124 | 160 | 160 |
| mmax. | | 74 | 105 | 132 | 161 | 193 | 253 | 295 |
| n | | 20 | 32 | 40 | 40 | 54 | 60 | 60 |
| o g6 | | | 8 | 10 | 12 | 12 | 18 | 18 |
| p | | 13.5 | 12 | 13 | 16 | 16 | 20 | 20 |
| q H7 | | | 18 | 20 | 20 | 26 | 30 | 30 |
| r | | 2 | 2.5 | 3 | 3 | 3 | 4 | 4 |
| s | | - | 5 | 6 | 6 | 7 | 8 | 8 |
| t | | 12 | 16 | 21 | 25 | 30 | 35 | 35 |
| Alpha α | | 6°36' | 6°36' | 3° | 4°30' | 4°30' | 4°30' | 4°30' |
| Beta β | | 21°36' | 21°36' | 18° | 19°30' | 16°30' | 19°30' | 14°30 |
| Jaw stroke in mm (without relocation) | | 4.8 | 6.2 | 6.8 | 7.5 | 9.4 | 12 | 12 |
| Weight in Kgs (approx.) | | 3.7 | 9.1 | 17 | 34 | 61 | 108 | 168 |
| Speed rpm | | 4000 | 3600 | 3000 | 2500 | 2000 | 1600 | 1000 |
| Moment of Interita GD2 in kpm2 | | 0.03 | 0.13 | 0.41 | 1.14 | 3,25 | 8.8 | 22 |
| Internal | MIN. | 27 | 65 | 69 | 90 | 90 | 125 | 155 |
| Clamping | MAX. | 128 | 177 | 219 | 251 | 310 | 398 | 483 |
| External | MIN. | 3 | 5 | 6 | 8 | 14 | 19 | 50 |
| Clamping | MAX. | 126 | 161 | 210 | 252 | 320 | 413 | 497 |



SIZE 103.3 a 63.3 72.2 90.4 130.4 130.3 82 4 b 36.5 c d g6 e HARD JAW fH7 g h ¢ iφ 14.5 14.5 j k I 7.5 m SIZE a 39.5 b C dg6 e fHII SOFT JAW 8.5 8.5 9.5 g hφ iφ 14.5 14.5 7.5 7,5 j 7.5 k



Guindy Machine Tools Limited